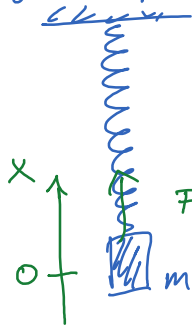


DGL bei der gedämpften Schwingung

Ungedämpfte Schwingung



$$F = m \cdot a = m \cdot \dot{v} = m \cdot \ddot{x}$$

$$-D \cdot x = m \cdot \ddot{x} \quad (7.4)$$

$$\ddot{x} + \frac{D}{m} x = 0$$

$$x = x(t) = \text{func}(t)$$

Ansatz

$$\text{z.B. } \underline{x(t)} = x_0 \cdot \cos(\omega_0 t) \quad \text{oder sin}$$

$$\dot{x} = -x_0 \sin(\omega_0 t) \cdot \omega_0$$

$$\underline{\underline{\ddot{x}}} = -x_0 \omega_0^2 \cos(\omega_0 t)$$

$$-x_0 \omega_0^2 \cos(\omega_0 t) + \frac{D}{m} x_0 \cos(\omega_0 t) = 0$$

$$-\omega_0^2 + \frac{D}{m} = 0$$

$$\omega_0 = \sqrt{\frac{D}{m}}$$

Ⓟ $m = 200g$

$$T_{10} = 11.7s$$

10 oscillationen

$$T = \underline{1.2s} \quad \omega_0^{200g} = \frac{2\pi}{T}$$

$m = 400g$

$$T_{10} = 21.4s$$

$$T = \underline{2.1s} \quad \omega_0^{400g} = \frac{2\pi}{T} \approx \frac{1}{2} \omega_0^{200g}$$

weil Massen verh. = 1:4 + $\sqrt{\quad}^4 \rightarrow \underline{\underline{1:2}}$

gedämpfte Schwingung

$$F_{\text{Reibung}} = k \cdot v \quad (\text{Stokes'sche Reibung})$$

$$\hookrightarrow v = \dot{x}$$

Bewegungsgleichung

$$m \ddot{x} + k \dot{x} + D x = 0$$

Erwartung: Amplitude nimmt ab

$$x_0 \mapsto x_0 e^{-\delta t}$$

(bei $\omega = \delta$)

$$x(t) = x_0 e^{-\delta t} \cos \omega t$$

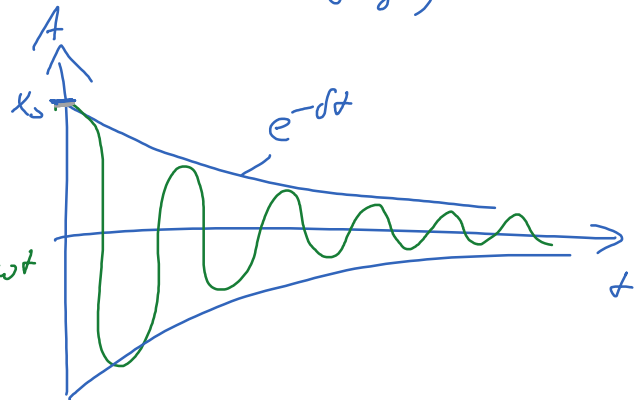
$$\dot{x}(t) = x_0 (-\delta) e^{-\delta t} \cos \omega t + x_0 e^{-\delta t} (-\omega) \sin \omega t$$

$$= x_0 e^{-\delta t} (-\delta \cos \omega t - \omega \sin \omega t)$$

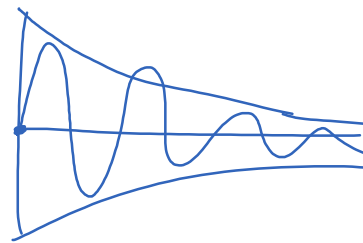
$$\ddot{x}(t) = x_0 \delta^2 e^{-\delta t} \cos \omega t + x_0 \delta e^{-\delta t} \omega \sin \omega t$$

$$+ x_0 \delta e^{-\delta t} \omega \sin \omega t - x_0 e^{-\delta t} \omega^2 \cos \omega t$$

$$= x_0 e^{-\delta t} [(\delta^2 - \omega^2) \cos \omega t + 2 \delta \omega \sin \omega t]$$



eben \sin -mäßig



Einsetzen: (in Bewegungsgl. geteilt durch m)

$$x_0 e^{-\delta t} [(\delta^2 - \omega^2) \cos \omega t + 2 \delta \omega \sin \omega t] \quad \ddot{x}$$

$$- \frac{k}{m} \delta \cos \omega t - \frac{k}{m} \omega \sin \omega t \quad \dot{x}$$

$$+ \frac{D}{m} \cos \omega t \quad x$$

$$\} \stackrel{!}{=} 0$$

\cos -Terme

\sin -Terme

$$2 \delta \omega \sin \omega t - \frac{k}{m} \omega \sin \omega t \stackrel{!}{=} 0$$

$$\delta^2 - \omega^2 - 2\delta^2 + \omega_0^2 = 0$$

$$\omega_0^2 - \delta^2 - \omega^2 = 0$$

$$2\delta \omega \sin \omega t - \frac{k}{m} \omega \sin \omega t = 0$$

$$2\delta - \frac{k}{m} = 0$$

$$\delta = \frac{k}{2m}$$

Schwingungsfreq. $\omega = \sqrt{\omega_0^2 - \delta^2}$



$$T_5 = 9.4 \text{ s}$$

400g

5 Schwingungen

$$T = \underline{1.8 \text{ s}}$$

Wack zu Dämpfung

fehler gemessen

